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☐	L4	robot$6 and KRL same program$ and control	0
☐	L3	robot$6 and kRLl and control	0
☐	L2	robot$6 and kRLl and program$ and control	0
☐	L1	robot$6 and krl same program$ and control	0

END OF SEARCH HISTORY

Key: IEEE JNL = IEEE Journal or Magazine, IEE JNL = IEE Journal or Magazine, IEEE CNF = IEEE Conference, IEE CNF = IEE Conference, IEEE STD = IEEE Standard

1. **Neural network architecture for robot hand control**
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